Raj Deshmukh

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• A P T I V •

EDUCATION	Purdue University, West Lafayette Ph.D., Aeronautics and Astronautics Engineering, 2020 GPA: 3.65/4.00 Dissertation: Data-driven Learning for Anomaly and Precursor Detection in Metroplex Airspace Oper- ations Major: Dynamics and Control, Minor: Systems Engineering
	 M.S., Aeronautics and Astronautics Engineering, 2017 GPA: 4.00/4.00 Thesis: Development of Optimal Kalman Consensus Filter and its Application to Distributed Hybrid State Estimation Major: Dynamics and Control, Minor: Systems Engineering
	Indian Institute of Technology Kharagpur, IndiaB.Tech. with Honors, Aerospace Engineering, 2015GPA: 8.49/10.00Thesis: Automatic Control of VTOL UAVMinor: Electronics & Electrical Communication EngineeringGraduated top of class with University Silver Medal
RESEARCH AREAS	 Multi-sensor fusion Multi-target tracking Hybrid system theory Distributed state estimation Probability and statistics Automotive systems Machine learning Predictive Airspace operations Airspace operations Iterative testing and test-bed deployment
PUBLICATIONS	Deshmukh, Raj , et al. "Distributed State Estimation for a Stochastic Linear Hybrid System over a Sensor Network." <i>IET Control Theory & Applications</i> 12.10 (2018): 1456-1464.
	Deshmukh, Raj , and Inseok Hwang. "Incremental-Learning-Based Unsupervised Anomaly Detection Algorithm for Terminal Airspace Operations." <i>Journal of Aerospace Information Systems</i> (2019).
	Deshmukh, Raj , et al. "Reactive Temporal Logic-Based Precursor Detection Algorithm for Terminal Airspace Operations." <i>Journal of Air Transportation</i> 28.4 (2020): 155-163.
	Deshmukh, Raj , et al. "Temporal Logic Learning-based Anomaly Detection in Metroplex Terminal Airspace Operations." <i>Transportation Research Part C: Emerging Technologies</i> 126 (2021): 103036.
	Deshmukh, Raj , Cheolhyeon Kwon, and Inseok Hwang. "Optimal Discrete-time Kalman Consensus Filter." 2017 American Control Conference (ACC). IEEE, 2017.
	Deshmukh, Raj , and Inseok Hwang. "Anomaly Detection Using Temporal Logic Based Learning for Terminal Airspace Operations." <i>AIAA Scitech 2019 Forum</i> (Finalist for Best Student Paper).
	Deshmukh, Raj , Dawei Sun, and Inseok Hwang. "Data-Driven Precursor Detection Algorithm for Ter- minal Airspace Operations." <i>FAA/Eurocontrol ATM Seminar 2019</i> (Best paper in Complexity track).
	Khan, Shiraz, Raj Deshmukh , and Inseok Hwang. "Optimal Kalman Consensus Filter for Weighted Directed Graphs." 2019 IEEE 58th Conference on Decision and Control (CDC). IEEE, 2019.
	Kim, Kwangyeon, Raj Deshmukh , and Inseok Hwang. "Development of Data-Driven Conflict Resolution Generator for En-Route Airspace." <i>Aerospace Science and Technology</i> (2019), under review.
	Khan, Shiraz, Raj Deshmukh , and Inseok Hwang. "Optimal Kalman Filter with Information-Weighted Consensus." <i>IEEE Transactions on Automatic Control</i> (2020), under review.
	Deshmukh, Raj , et al. "Enhancing the Effectiveness of Network Centric Operations using System-of-Systems Modeling and Analysis Technique." Presentation at 10th Annual Conference of the Asia-Pacific Council on Systems Engineering (2016).

PROJECTS

Aptiv, Troy Active Safety & User Experience

• Object Tracking Developer

- Responsible for designing and implementing production-level automotive perception algorithms that use radar and camera sensors for multi-sensor multi-target data fusion
- Implementing object tracking to enable advanced-driver assistance systems (ADAS) features designed for OEMs, and helped root-cause and resolve issues found by OEMs during real-world testing
- Developing sensor monitoring algorithms that safely disable ADAS features upon loss of signal quality by ascertaining their plausibility before perception-related processing
- Ensuring industry-related quality assurance by running functional tests for ASPICE and MISRA compliance

Purdue University, West Lafayette

School of Aeronautics and Astronautics

- Graduate Research Assistant
- Graduate Teaching Assistant
 - Collaborated with supervisors and colleagues for designing course instruction materials for sophomore and junior undergraduate students
 - Maintained webcourses on Blackboard, a digital instruction platform
 - Consistently provided feedback on assignments during weekly office hours, proctored and graded exams, entered and maintained grades, and provided review preparation for final exam

Purdue University, West Lafayette RESEARCH

Purdue Flight Dynamics & Control/Hybrid Systems Lab

- Optimal Distributed State Estimation - Addressed decade-long problem of suboptimality in Kalman consensus filtering, finding applications
 - in sensor network theory and network fault detection
 - Developed optimal Kalman consensus filter applied to stochastic LTI and hybrid targets; documented as master's thesis, with advisor Prof. Inseok Hwang
 - Extended application of distributed state estimation to network with naïve sensors
 - Developed measurement vector fusion approach, enabling consensus on measurements as well as estimates
- NASA Big Data Analytics Project Nov '17 - Sep '19 - Investigated use of data-driven methods to discover previously unknown safety threats within extremely large, heterogeneous datasets representing operations of the National Airspace System
 - Designed and implemented machine learning-based anomaly detection and prognosis algorithms to detect operational and safety related issues using real air traffic datasets recorded at LGA, JFK and EWR airports in New York metroplex
 - Contributed to development of a rapidly deployable, scalable, and versatile air traffic management (ATM) simulation and test environment along with Mosaic ATM and Honeywell International Inc., helping advance decision-making capabilities to improve ATM on a grand scale
- Contributions to project documented as doctoral dissertation, with advisor Prof. Inseek Hwang
- NASA Next-Gen Concept Technology and Development Project May '16 - Oct '17 - Investigated methods to identify and classify resolutions for detected conflicts in historical aircraft track data, collaborating with Optimal Synthesis Inc.
 - Designed novel hierarchical supervised learning algorithm employed within decision-aiding tool to generate conflict resolution strategies learned from flight plans and historical track data
- Relaxation of Min-max Strategies to Control Autonomous Vehicles Jan '16 - May '16
 - Investigated into a dynamically evolving balance between performance and safety of connected autonomous ground vehicles, characterized by likelihood of collision, as a novel extension to conventional min-max navigation strategies

Mar '20 - present

Aug '15 - Jan '20

Aug '15 - Jul '17 & Jun '18 - Sep '19

Aug '17 - May '18 & Aug '19 - Dec '19

National Aerospace Laboratories, India

Flight Mechanics and Control Division

• Drag Polar Estimation of a High Performance Aircraft Using Crash Data Recorder

- Undertook performance analysis of fly-by-wire aircraft using parameter estimation techniques - Lift, drag, and pitching characteristics were estimated using model-based and non-model-based approaches using flight test data recorded in crash data recorder

IIT Kharagpur, India

Boeing Company, U.S.A.

- Phase 6 Boeing Students' Project Mar '14 - Feb '15 - Project requiring design, fabrication, and testing of semi-autonomous quadrotor capable of way
 - point navigation Mar '13 - Feb '14
- Phase 5 Boeing Students' Project
 - Project involving design and flight testing of micro-air vehicle capable of waypoint navigation
 - Designed novel wing planform with winglets using flying wing configuration
- SKILLS
- Programming languages and scientific software: MATLAB, C++, Python, R, Simulink, SolidWorks • Documentation and technical writing: LATEX, MS Office, Polarion
- SCHOLASTIC University Silver Medal

HONORS

Awarded university silver medal for graduating at top of undergraduate class

Jagadis Bose Scholar

Scholarship by Jagadis Bose National Science Talent Search; aims to identify and nurture young talented students of science, medicine and engineering with potential to become leaders in innovation excellence; one among 55 scholars in India